OWI PC Interface For Robotic Arm Trainer (Model Number: IBM-007)

Please read this booklet in its entirety before operating this unit.

The Robotic Arm Trainer Interface is an application that enables you to issue commands from the computer to the Robotic Arm Trainer. You can use the application from a DOS prompt or install in Windows © (Win 95 or Win 98). The Robotic Arm Trainer Interface enables you also to save the program and play it back again. The Robotic Arm Trainer can be activated using the Manual Controller or via the PC program. The Robotic Arm Trainer has three modes of operation:

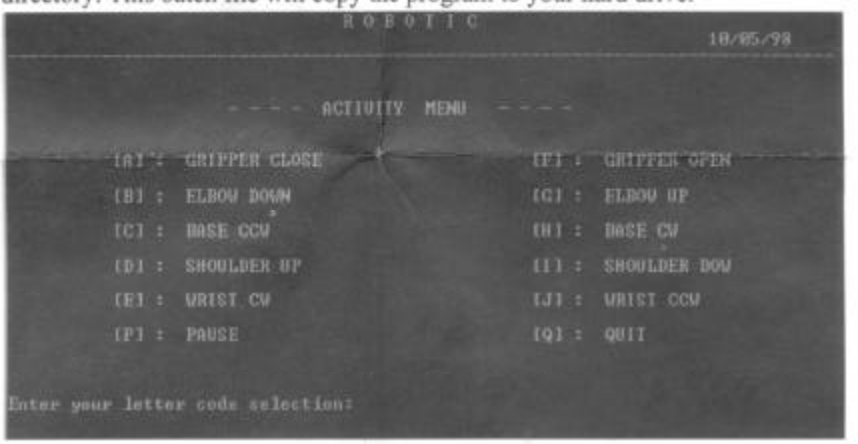
Manual: using the controller.
Direct: using computer input.
Program: using a pre-recorded Windows © program file.

COMPUTER CONTROL:

Dos Installation

To install the program into your DOS drive. Insert Disk 2/2 and type in **A:\DOSSET A: C:\ROBOT,** then press **ENTER.**

Where **A:**: is your source diskette address and **C:\ROBOT** is the address of your destination directory. This batch file will copy the program to your hard drive.



Dos Operation:

From the root directory C:, type **CD ROBOT** press **ENTER** then type **ROBOTIC** then press **ENTER**. The above screen will appear. Make sure the slide switch on the interface board is in the "ON" position. To operate the robot, simply press the appropriate key from your keyboard to activate the needed command. Press on the "Q" key to quit the program and return the Robotic Arm Trainer into Pause Mode.

Windows Installation

To install the windows 9x program: place disk 1 in the 3.5 floppy drive and click the **START** button , then type **a:\setup.exe** click **OK**. Follow the instruction of the setup program, and it will copy the Robotic Arm Trainer Interface Program to your directory and add an icon to your desktop. After Installing the program you will be able to launch it by double clicking the **ROBOT** icon. Once the program is started you will have access to 2 windows: The Main Window and the Program Play Window:

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